



What do we know about policy costs? How can we learn more?

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Outline

- The challenge of cost projections.
- A review of what we know.
- Reflecting on the challenge.
- An adaptive management problem?
- Implementation possibility?
- Conclusion



Challenge of cost projection



- Knowing the present baseline:

- Economic
- Environmental



- Knowing the future baseline absent intervention.

- Economic
- Environmental



- Knowing impacts of intervention.

- Economic
- Environmental



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Review of what we know 1



- For industry:

- Governments tend to overestimate baseline emissions.
- Command & control schemes have cost about as much as expected per unit emission controlled.
- Flexible/incentive schemes have tended to be less expensive than expected.
- Trading has rarely, if ever, been why controls have been less costly to achieve.
- Porter's hypothesis is not borne out for any industry group. On average \$1 in control cost lead to \$18 production cost savings.



- For households:

- Policy costs have been systematically under-estimated.
- 2/3 of US households do not use any energy savings information when purchasing appliances.
- 1/7 of US households spend > 10% of income on residential energy costs. Why would then not exercise informed choice?
- Exposure to full market forces only changes the fraction who exercise informed choice from 1/4 to 1/3.



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Review of what we know 2



- Climate models now routinely reflect parametric uncertainties but rarely address structural uncertainties in how we conceptualize the way the world works.



- The climate policy costing models have grown more sophisticated but still struggle with:

- what the economic baseline will be;
- how to represent technical change and its response to policy;



- No end of sophistication will stop models from being surprised by:

- new science such as net impacts of converting a farm to a forest on the climate system (Pielke 2002).
- new applications of old technology (industrial carbon separation and sequestration).



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Review of what we know 3



- The good news is that from a technical standpoint back-stop control costs, even draconian controls in 2025, are unlikely to be higher than \$250/tC.

- The bad news is that there has been negligible behavioural response to oil price rises in excess of \$120/tC since January 1999.



- However climate policy can have significant announcement effect. For example, the UK share of new diesel car registrations has doubled from 13% to 26% in response to announced new tax policy on automobile ghg emissions* starting in 2002. Unfortunately, such effects are rarely, if ever, modelled.



- * This outcome also exemplifies grave policymaker error. It will cause significant additional mortality and morbidity in the UK by being implemented *before* the availability of automobiles capable of meeting Euro IV particulate emission standards.



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Reflecting on the challenge



- GHG controls are alien territory to both firms and regulators

- why expect firms to excel at controls (under any implementation scheme) when there is no track record?
- Why expect regulators to get the policy right?



- Firms are heterogeneous in their innovation strategy (from the radical innovators to the incremental modifiers)

- why treat everyone the same?
- Why not exploit the differences creatively?



- Unlike most previous experience, GHG control regimes and economic systems are not conterminous.

- many have commented on the problem of leakage.
- Real-politics of trade may lead to conflict over government R&D and capital turnover incentives to increase buy-in of policy.



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An adaptive management problem?



REALITY

- Asymmetry of information between regulator and regulatee.
- A population that can be partitioned into:
 - A group of innovators in technology & management.
 - A group of rapid adopters once the path to success is charted.
 - A group of laggards who will resist to the end.



- By proposing "one size fits all" policies, we get endless resistance.



THEORY

- Continuous learning about the system.
- Careful interventions designed to reveal system properties and meet objectives.
- Careful monitoring.
- Periodic re-evaluation of objectives.
- Iterative refinement of interventions.

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Implementation possibility!



- Phase I: Start small policy experiments with *innovators*. Being careful to:
 - limit their risks.
 - monitor costs and impacts.
 - refine goals and governing regulations to reflect the technically, socially and economically desirable.
- Phase II: Promote* diffusion of the "innovative steps" that lead to best practice compliance under flexible schemes.
- Phase III: Develop command & control regulations based on best practice for laggards.
- Phase Ia: revisit the goals and start again...



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Conclusion



- In public policy the problem of *free-riders* is well known.
- A scheme is proposed where *innovator agents* (firms, farms, foresters, municipalities, ...) in partnership with regulators become *free-drivers* helping chart a course towards meeting new policy objectives.
 - A carefully selected set of experiments will help reveal best policy design.
 - it will also generate an empirical basis from which control costs can be more reliability estimated.
- In this scheme:
 - flexibility measures are offered where it can be best used.
 - inflexibility is imposed where flexibility is abused.



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